

LISTING OF THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

Claims 1-7 (canceled).

8. (new) A method for closed-loop speed control of an internal combustion engine-generator unit during a starting process, comprising the steps of: presetting a set speed ($nM(SW)$) by means of a set run-up ramp ($HLR(SW)$); computing a control deviation from the set speed ($nM(SW)$) and an actual speed ($nM(IST)$); determining a set injection quantity (QSW) for controlling the actual speed ($nM(IST)$) from the control deviation by means of a speed controller; and, determining an actual run-up ramp ($HLR(IST)$) from the actual speed ($nM(IST)$), ($HLR(IST) = f(nM(IST))$), and setting this as the set run-up ramp ($HLR(SW)$).

9. (new) The method for closed-loop speed control in accordance with claim 8, including determining the actual run-up ramp ($HLR(IST)$) from a change in speed ($dn(i)$, $i = 1, \dots, n$) of the actual speed ($nM(IST)$) within an assigned time interval ($dt(i)$).

10. (new) The method for closed-loop speed control in accordance with claim 9, including computing the actual run-up ramp ($HLR(IST)$) from the change in speed ($dn(i)$) during the time interval ($dt(i)$) by taking the mean value.

11. (new) The method for closed-loop speed control in accordance with claim 10, wherein the actual run-up ramp ($HLR(IST)$) and a constant (K) are added ($HLR(SW) = HLR(IST) + K$).

12. (new) The method for closed-loop speed control in accordance with claim 8, further including checking to determine whether the actual run-up ramp ($HLR(IST)$) is within a tolerance band (TB).

13. (new) The method for closed-loop speed control in accordance with claim 12, including setting an error mode (FM) if the actual run-up ramp (HLR(IST)) is outside the tolerance band (TB).

14. (new) The method for closed-loop speed control in accordance with claim 8, including setting the actual run-up ramp (HLR(IST)) as the set run-up ramp (HLR(SW)) at least when an idling speed (nLL) has been reached.